

Course Overview

<http://www.ee.nmt.edu/~erives/>

Texts: Freescale Databooks on the MC9S12 (You can pick up the Freescale data sheets at the end of class today)

The HCS12/9S12: An Introduction to Software and Interfacing (Recommended)

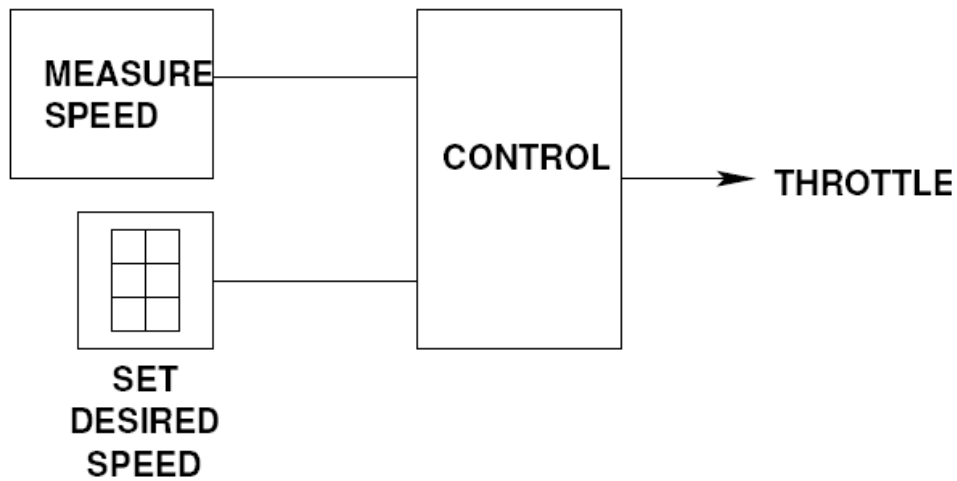
- Introduction to the MC9S12 Microcontroller
- Binary and Hexadecimal Numbers
- Assembly Language Programming
- C Language Programming
- Introduction to MC9S12 Internal Peripherals
 - The MC9S12 Timer Subsystem
 - Interrupts using the Timer Subsystem
 - The MC9S12 Pulse Width Modulator Subsystem
- The MC9S12 Expanded Mode
 - Address and Data Buses and Timing
 - Adding Memory and External Peripherals
 - Interfacing to the MC9S12
- More MC9S12 Internal Peripherals
 - The A/D Converter Subsystem
 - The Serial Peripheral Interface
 - The Serial Communications Interface
- Using the MC9S12 in a Control Application

Lab Overview

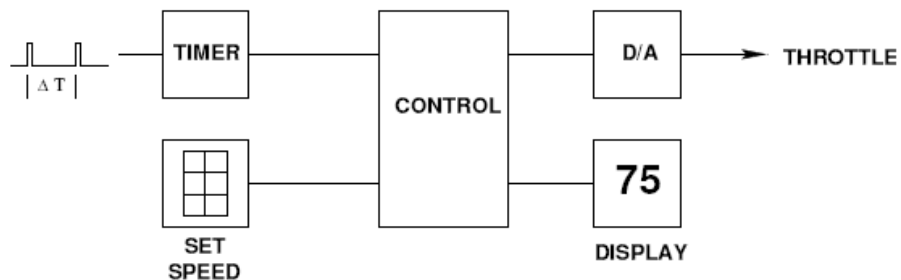
- The lab instructors are Dr. Scott Teare and Dr. Anders Jorgensen. The lab meets Monday and Wednesday afternoons. No labs this week.
- Lab handouts will be posted on Dr. Teare's EE 308 website:
- The 9S12 evaluation kits will be passed out in lab next week.
- You need to bring a bound lab notebook to the first lab.
- There will be a prelab for each lab. This must be done and turned in at the start of your lab section. The lab TA will verify that you have completed the prelab.

- **Introduction to Microprocessors and Microcontrollers.**
- Huang, Sections 1.2, 1.3
 - Course Overview
 - Cruise Control Block Diagrams and Flowchart
 - Block Diagrams of Simple Microprocessor and Microcontroller
 - Harvard architecture and Princeton (Von Neuman) architecture microprocessor block diagrams
 - Memory map for a Princeton architecture microprocessor

AUTOMOBILE CRUISE CONTROL

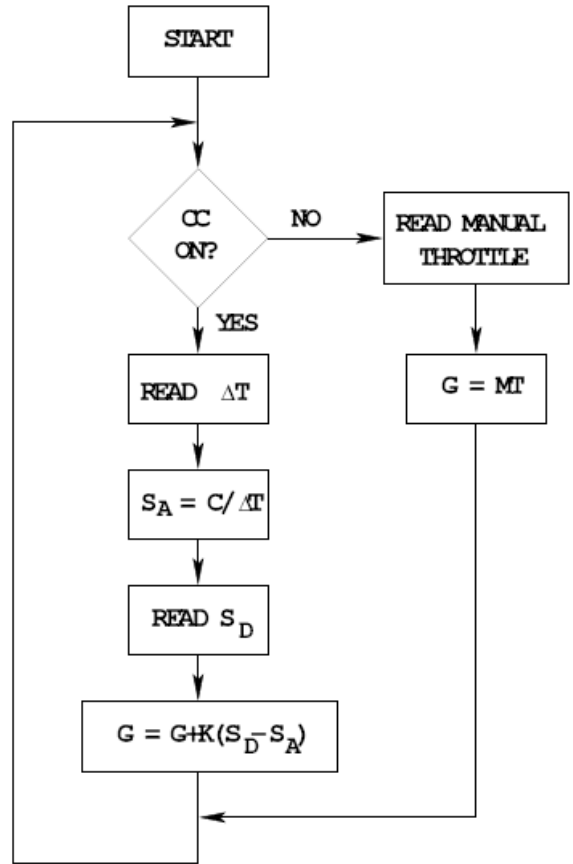


AUTOMOBILE CRUISE CONTROL

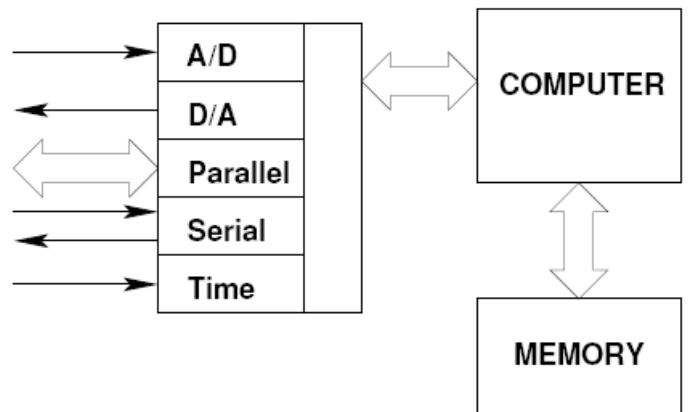


ΔT = time for one revolution of wheel.

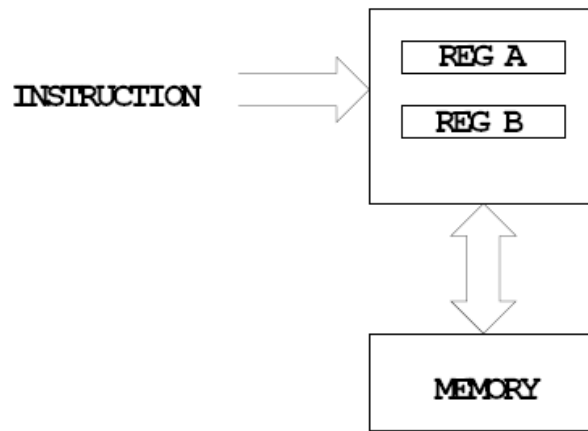
Speed = $C/\Delta T$, where C is the circumference of the wheel



MICROCONTROLLER

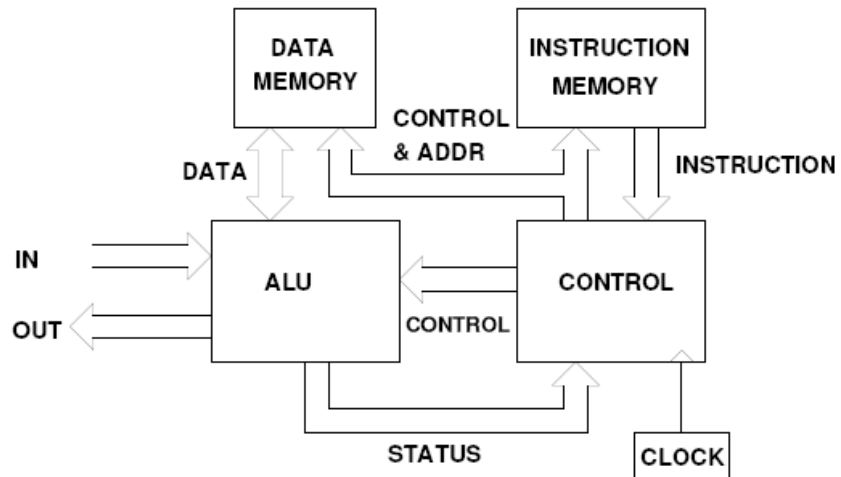


SIMPLE MICROPROCESSOR

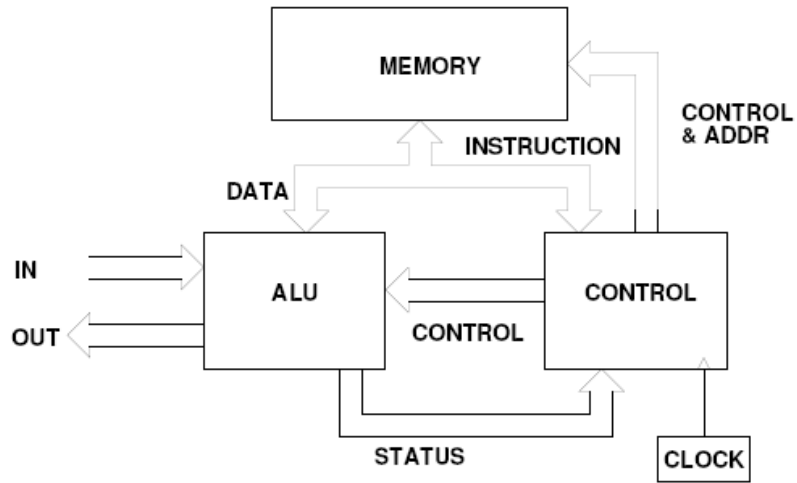


INSTRUCTION	ACTION
18 06	$(A) + (B) \Rightarrow A$
87	$0 \Rightarrow A$
5A 05	$(A) \Rightarrow \text{Address 5}$

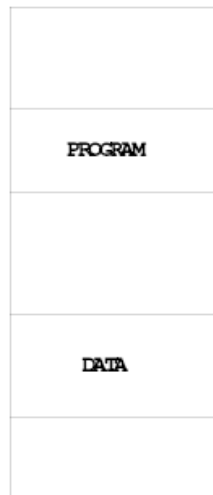
HARVARD ARCHITECTURE MICROPROCESSOR



PRINCETON (VON NEUMAN) ARCHITECTURE MICROPROCESSOR



MEMORY MAP (Princeton Architecture)



Function of memory determined by programmer

Binary	Hex	Decimal
0000	0	0
0001	1	1
0010	2	2
0011	3	3
0100	4	4
0101	5	5
0110	6	6
0111	7	7
1000	8	8
1001	9	9
1010	A	10
1011	B	11
1100	C	12
1101	D	13
1110	E	14
1111	F	15

Convert Binary to Decimal

1111011_2

$$1 \times 2^6 + 1 \times 2^5 + 1 \times 2^4 + 1 \times 2^3 + 0 \times 2^2 + 1 \times 2^1 + 1 \times 2^0$$

$$1 \times 64 + 1 \times 32 + 1 \times 16 + 1 \times 8 + 0 \times 4 + 1 \times 2 + 1 \times 1$$

123_{10}

Convert Hex to Decimal

$82D6_{16}$

$$8 \times 16^3 + 2 \times 16^2 + 13 \times 16^1 + 6 \times 16^0$$

$$8 \times 4096 + 2 \times 256 + 13 \times 16 + 6 \times 1$$

33494_{10}