

	1	2	3	4	5	6	7	8
Tues	1/18 (L) Introductory lecture [Tubesing, EI-Osery]	1/25 (L) Industry design & teamwork lecture [Bond]	2/1 (C) Initial design intentions	2/8 (C) Down selection of sensors	2/15 TBA	2/22 MSEC 101 (P) Preliminary Design Review	3/1 MSEC 101 (L) PCB tools, design, and prep for manufacturing [Tubesing]	3/8
Thurs	1/20 (W) (D) Assemble robot & test with H-bridge	1/27 (H) Assignment 1 (W)	2/3 (H) Assignment 2 (D) Initial test of locomotion/ctrl system. Make robot drive in square	2/10 TBA	2/17 TBA	2/24	3/3 TBA	3/10 (D) Sensor integration & testing
	9	10	11	12	13	14	15	16
Tues	3/22	3/29 (C) Eval of approach	4/5 (D) Midterm functionality eval (working prototype)	4/12 TBA	4/19 TBA	4/26 TBA	5/3 (D) Final design & functionality eval	5/10 Finals Week
Thurs	3/24	3/31 TBA	4/7 (W) testing & redesign	4/14 TBA	4/21 TBA	4/28 TBA	5/5 MSEC 101 (P) Final Presentation	5/12 Finals Week