EE 565: Position, Navigation and Timing
Introduction to Navigation

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    - need to initialized and then "integrate" the Δ's
    - Inertial sensors measure the Δ's without requiring an external reference

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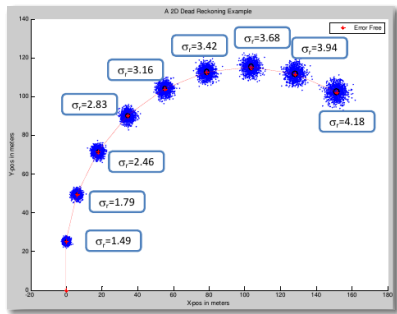
PVA needed in terms of local datum
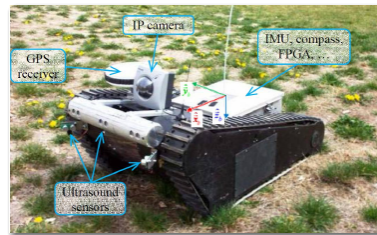
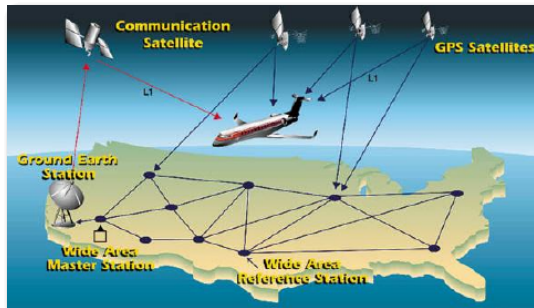DARPA grand challenge

PVA needed in terms of local datum

DARPA grand challenge

SOCOM Robot (EE NMT project)

Earth Centered Earth Fixed Coordinate System

Earth Centered Inertial Coordinate System

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2. How should I describe my location?
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3. When answering the question "where am I?" the *wrt* must be very clearly defined!!
   - Lead in to the notion of coordinate systems