

- **Dragon12 LCD Displays**
- Hantronix_CLD.PDF data sheet (Dragon12 CD-ROM)
 - Using the Dragon12 LCD display

Dragon12 LCD Display

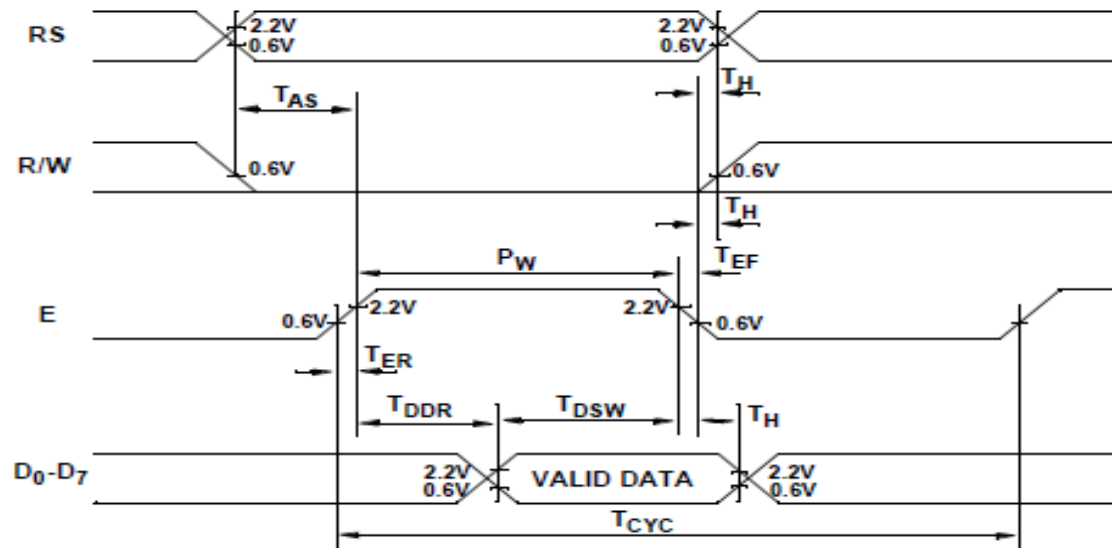
- The Dragon12 board has a 16 character x 2 line display
- Each character is a 5x7 bit matrix
- A controller chip (Hitachi HD44780) converts ASCII characters to 5x7 bit image
- The controller chip is connected to **Port K** of the MC9S12
 - Bit 0 of Port K (PK0) selects command (0) or data (1)
 - Bit 1 of Port K (PK1) enables the data transfer
 - Bits 5 through 2 Port K (PK5-2) contain the data
 - Bit 7 of Port K (PK7) can be used to select read or write. The LCD on the Dragon12 board is set up for write only; you need to cut a trace to be able to read from the LCD.
- Use of the display is discussed in the **Hatronic_LCD2.pdf** datasheet which is on the CD-ROM which came with the Dragon12 board.

- You can send commands or data to the controller chip to control the LCD display.
- These commands and data are detailed in the Hatronix_LCD2.pdf datasheet.
- The commands are:
 - Clear display and return cursor to home (upper left)
 - Cursor home (don't clear display)
 - Entry mode (move cursor left or write)
 - Display on/off – turns display on or off, cursor on or off, cursor blink
 - Cursor/display shift – move cursor or shift display, which direction
 - Function set – bus data width (8 or 4), number of display lines (1 or 2), font size 6x8 or 5x7)
 - Set CG RAM address – set address of CG (Character Generation) RAM to generate your own characters
 - Set DD RAM Address – set address of DD (Data Display) RAM to display characters
 - Read busy flag and address (we can't use)
 - Write data to DD RAM or CG RAM
 - Read data from DD RAM or CG RAM (we can't use)

Dragon12 LCD Display

- The LCD display can use either 8-bit or 4-bit data bus. The Dragon12 board uses a **4-bit bus, so it takes two transfers to send one command**
- The Dragon12 board is set so that you cannot read from the display; you can only write to it.
- When you write a command, you need to wait until the command has been executed by the LCD controller. The Busy Flag (from Read Busy Flag command) tells when the command is done. **We cannot read Busy Flag, so we have to wait specified time before proceeding.**
- To write to the controller, need to:
 1. Set RS (PK0) to 0 for command, 1 for data
 2. Set R/\hat{W} (On Dragon12, R/\hat{W} tied low for write only)
 3. Put 4 MSB on Port K bits 5-2
 4. Bring E (PK1) high for at least 230 ns (P_w)
 5. Bring E (PK1) low
 6. Put 4 LSB on Port K bits 5-2
 7. Bring E (PK1) high for at least 230 ns
 8. Bring E (PK1) low
 9. Wait specified amount of time for execution to complete

DATA WRITE



TIMING CHARACTERISTICS

| ITEM | SYMBOL | MAX. | MIN. | UNIT |
|-----------------------|-----------------------------------|------|------|------|
| ENABLE CYCLE TIME | T _{CYC} | | 500 | nS |
| ENABLE PULSE WIDTH | P _W | | 230 | nS |
| ENABLE RISE/FALL TIME | T _{ER} , T _{EF} | 20 | | nS |
| RS, R/W SET UP TIME | T _{AS} | | 40 | nS |
| DATA DELAY TIME | T _{DDR} | 360 | | nS |
| DATA SETUP TIME | T _{DSW} | | 60 | nS |
| HOLD TIME | T _H | | 10 | nS |

Dragon12 LCD Display

- To use LCD display
 1. Give command **0x28**: Tell controller our display uses 4-bit data, 2-line display, 5x7 font
 2. Give command **0x0F**: Turn on display, use cursor, blink cursor
 3. Give command **0x06**: Move cursor to right after writing a character
 4. Give command **0x01**: Clear screen, move cursor to home (upper left character)
 5. Wait for at least **1.64 ms**
- After display is set up, you can write characters to display

Handling LCD's & LCD Modules

- Do not touch display are with bare hands
- Do not touch exposed polarizer with hard objects
- Do not expose the CMOS IC's to static electricity
- Avoid exposing the module to excessive shock or pressure
- Do not allow the storage temperature to exceed the specified range

File lcd.h:

```
#define LCD_DAT PORTK    /*Port K drives LCD data pins, E, and RS */
#define LCD_DIR DDRK    /*Direction of LCD port */
#define LCD_E 0x02      /*LCD E signal */
#define LCD_RS 0x01     /*LCD Register Select signal */

#define CMD 0           /*Command type for put2lcd */
#define DATA 1        /*Data type for put2lcd */
```

/* Prototypes for functions in lcd.c */

```
void openlcd(void);      /* Initialize LCD display */
void put2lcd(char c, char type); /*Write command or data to LCD */
void puts2lcd (char *ptr); /* Write a string to the LCD display */
void delay_50us(int n);  /* Delay n 50 microsecond intervals */
void delay_1ms(int n)   ; /* Delay n 1 millisecond intervals */
```

File lcd.c:

```
#include "derivative.h"
#include "lcd.h"

void openlcd(void)
{
    LCD_DIR = 0xFF;      /* configure LCD_DAT port for output */
    delay_1ms(100);     /* Wait for LCD to be ready */
    put2lcd(0x28,CMD);   /* set 4-bit data, 2-line display, 5x7 font */
    put2lcd(0x0F,CMD);  /* turn on display, cursor, blinking */
    put2lcd(0x06,CMD);  /* move cursor right */
    put2lcd(0x01,CMD)   /* clear screen, move cursor to home */
    delay_1ms(2);       /* wait until "clear display" command */
                       /* complete */
}

void puts2lcd (char *ptr)
{
    while (*ptr) {      /* While character to send */
        put2lcd(*ptr,DATA); /* Write data to LCD */
        delay_50us(1);    /* Wait for data to be written */
        ptr++;            /* Go to next character */
    }
}

void put2lcd(char c, char type)
{
    char c_lo, c_hi;

    c_hi = (c & 0xF0) >> 2; /* Upper 4 bits of c */
    c_lo = (c & 0x0F) << 2; /* Lower 4 bits of c */
    if (type == DATA) LCD_DAT |= LCD_RS; /* select LCD data */
                                       /*register */
}
```



```
else LCD_DAT &= (~LCD_RS);    /* select LCD command */
                               /* register */
if (type == DATA)
    LCD_DAT = c_hi|LCD_E|LCD_RS; /* output upper 4 bits, */
                               /* E, RS high */
else
    LCD_DAT = c_hi|LCD_E;      /* output upper 4 bits, E, */
                               /* RS low */
LCD_DAT |= LCD_E;             /* pull E signal to high */
__asm(nop);                   /* Lengthen E */
__asm(nop);
__asm(nop);
LCD_DAT &= (~LCD_E);          /* pull E to low */
if (type == DATA)
    LCD_DAT = c_lo|LCD_E|LCD_RS; /* output lower 4 bits, E,
                               RS high */
else
    LCD_DAT = c_lo|LCD_E; /* output lower 4 bits, E, RS low */
LCD_DAT |= LCD_E; /* pull E to high */
__asm(nop); /* Lengthen E */
__asm(nop);
__asm(nop);
LCD_DAT &= (~LCD_E); /* pull E to low */
delay_50us(1);       /* Wait for command to */
                     /* execute */
}

#define D50US 133    /* Inner loop takes 9 cycles; */
void delay_50us(int n) /* need 50x24 = 1200 cycles */
{
    volatile int c;

    for (;n>0;n--)
        for (c=D50US;c>0;c--);
}
```

```
void delay_1ms(int n)
{
    for (;n>0;n--) delay_50us(200);
}
```

File main.c:

```
#include <hidef.h>           /* common defines and macros */
#include "derivative.h"      /* derivative-specific definitions */
#include "lcd.h"

void main(void) {
    char *msg1 = "Hello, World!";
    char *msg2 = "From Bill";
    openlcd();              // Initialize LCD display
    puts2lcd(msg1);         // Send first line
    put2lcd(0xC0,CMD);     // move cursor to 2nd row, 1st column
    puts2lcd(msg2);        // Send second line
    __asm(swi);
}
```