Partial solution to the review problem of Dec. 5, 2018

| $\begin{array}{c}\text { Present } \\ \text { state } \\ y_{2} y_{1}\end{array}$ | Next state |  | Output |
| :---: | :---: | :---: | :---: |
|  | $w=0$ | $w=1$ |  |
| 00 | 10 | $Y_{1}$ | $Y_{2} Y_{1}$ |$]$


| Present <br> state | Flip-flop inputs |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | $w=0$ |  | $w=1$ |  | Output |
|  | $J_{2} K_{2}$ | $J_{1} K_{1}$ | $J_{2} K_{2}$ | $J_{1} K_{1}$ |  |
| 00 | $1 d$ | $0 d$ |  | $1 d$ | 0 |
| 01 |  | $d 0$ | $0 d$ |  | 0 |
| 10 | $d 0$ |  |  | $0 d$ | 0 |
| 11 |  | $d 1$ | $d 1$ | $d 0$ | 1 |

$$
\begin{aligned}
J_{2} & =\bar{y}_{1} \\
K_{2} & =w \\
J_{1} & =\bar{w} y_{2}+w \bar{y}_{2} \\
K_{1} & =J_{1}
\end{aligned}
$$

$$
z=y_{1} y_{2}
$$

