Lecture 11

February 10, 2012

Using the Stack and the Stack Pointer

- The Stack and the Stack Pointer
- The stack is an area of memory used for temporary storage
- The stack pointer points to the last byte pushed onto the stack
- Some instructions which use the stack
- How data is pushed onto and pulled off of the stack.
- Subroutines and the Stack
- An example of a simple subroutine
- Using a subroutine with PORTA to make a binary counter on LEDs

The Stack and the Stack Pointer

• Sometimes it is useful to have a region of memory for temporary storage, which does not have to be allocated as named variables.

- When we use subroutines and interrupts it will be essential to have such a storage region.
- Such a region is called a *Stack*.
- The Stack Pointer (SP) register is used to indicate the location of the last item put onto the stack.
- When you put something onto the stack (push onto the stack), the SP is decremented before the item is placed on the stack.
- When you take something off of the stack (pull from the stack), the SP is incremented after the item is pulled from the stack.
- Before you can use a stack you have to initialize the Stack Pointer to point to one value higher than the highest memory location in the stack.
- For the MC9S12 put the stack at the top of the data space
 - For most programs, use \$1000 through \$2000 for data.
 - For this region of memory, initialize the stack pointer to \$2000.
 - If you need more space for data and the stack, and less for your program, move the program to a higher address, and use this for the initial value of the stack pointer.

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- Use the LDS (Load Stack Pointer) instruction to initialize the stack point.
- The LDS instruction is usually the first instruction of a program which uses the stack.
- The stack pointer is initialized only one time in the program.
- For microcontrollers such as the MC9S12, it is up to the programmer to know how much stack his/her program will need, and to make sure enough space is allocated for the stack. If not enough space is allocated the stack can overwrite data and/or code, which will cause the program to malfunction or crash.

The stack is an array of memory dedicated to temporary storage

SP points to location last item placed in block

	\	SP decreases when you put item on stack				
0x1EF5 0x1EF6					ou pull item from 000 as initial SP:	
0x1EF7 0x1EF8		S'	FACK:	EQU LDS	\$2000 #STACK	
0x1EF9		A				_ ∏ в
0x1EFA 0x1EFB		D				
0x1EFC		X				
0x1EFD 0x1EFE		Y				
0x1FFF		SP				
0x1F00 0x1F01		PC				
0x1F02				CCR		
0x1F03						
	\					

An example of some code which uses the stack

(LDS #STACK)

Stack	Pointer:	
-------	----------	--

Initialize ONCE before first use

Points to las	st used storaç	ge location				
Decreases v	vhen you put	something on st	tack			
Increases w	hen you take	something off s	tack			
			STACK:	equ \$2	2000	
0x1FF5			CODE:	org \$20	000	
0x1FF6						
0x1FF7				lds	#STACK	
0x1FF8				ldaa	#\$2e	
0x1FF9				ldx psha	#\$1254	
0x1FFA				pshx		
0x1FFB				cIra Idx	#\$ffff	
0x1FFC				CODE	THAT USES A &	X
0x1FFD				pulx		
0x1FFE				pula		
0x1FFF		A				
0x2000		_]
		Х				
		SF	-			

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PSHA

Push A onto Stack

PSHA

 $\textbf{Operation} \quad (SP) - \$0001 \Rightarrow SP$

 $(\mathsf{A}) \Longrightarrow \mathsf{M}_{\mathsf{SP}}$

Decrements SP by one and loads the value in A into the address to which SP points.

Push instructions are commonly used to save the contents of one or more CPU registers at the start of a subroutine. Complementary pull instructions can be used to restore the saved CPU registers just before returning from the subroutine.

CCR

Effects

S	Х	Н	ı	N	Z	٧	С
-	-	-	-	-	-	-	-

Code and

CPU Cycles

Source Form	Address Mode	Machine Code (Hex)	CPU Cycles
PSHA	INH	36	0s

Subroutines

• A subroutine is a section of code which performs a specific task, usually a task which needs to be executed by different parts of a program.

- Example:
 - Math functions, such as square root
- Because a subroutine can be called from different places in a program, you cannot get out of a subroutine with an instruction such as

jmp label

because you would need to jump to different places depending upon which section of code called the subroutine.

- When you want to call the subroutine your code has to save the address where the subroutine should return to. It does this by saving the *return address* on the stack.
 - This is done automatically for you when you get to the subroutine by using the JSR (Jump to Subroutine) or BSR (Branch to Subroutine) instruction. This instruction pushes the address of the instruction following the JSR (BSR) instruction on the stack.
- After the subroutine is done executing its code it needs to return to the address saved on the stack.
 - This is done automatically for you when you return from the subroutine by using the RTS (Return from Subroutine) instruction. This instruction pulls the return address off of the stack and loads it into the program counter, so the program resumes execution of the program with the instruction following that which called the subroutine.

The subroutine will probably need to use some MC9S12 registers to do its work. However, the calling code may be using its registers for some reason — the calling code may not work correctly if the subroutine changes the values of the MC9S12 registers.

- To avoid this problem, the subroutine should save the MC9S12 registers before it uses them, and restore the MC9S12 registers after it is done with them.

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BSR

Branch to Subroutine

BSR

 $\textbf{Operation} \quad (SP) - \$0002 \Rightarrow SP$

 $RTN_{H}:RTN_{L} \Rightarrow M_{SP}:M_{SP+1}$ $(PC) + \$0002 + rel \Rightarrow PC$

Sets up conditions to return to normal program flow, then transfers control to a subroutine. Uses the address of the instruction after the BSR as a return address.

Decrements the SP by two, to allow the two bytes of the return address to be stacked.

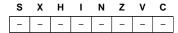
Stacks the return address (the SP points to the high byte of the return address).

Branches to a location determined by the branch offset.

Subroutines are normally terminated with an RTS instruction, which restores the return address from the stack.

CCR

Effects



Code and CPU

Cycles

Source Form	Address Mode	Machine Code (Hex)	CPU Cycles
BSR rel8	REL	07 rr	SPPP

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RTS

Return from Subroutine

RTS

Operation $(M_{SP}):(M_{SP})$

 $\begin{array}{l} (M_{SP}) : (M_{SP+1}) \Longrightarrow PC_H : PC_L \\ (SP) + \$0002 \Longrightarrow SP \end{array}$

Restores the value of PC from the stack and increments SP by two. Program execution continues at the address restored from the stack.

CCR

Effects

S	Х	Н	ı	N	Z	٧	С
_	-	-	-	-	-	-	-

Code and

CPU Cycles

Source Form	Address Mode	Machine Code (Hex)	CPU Cycles
RTS	INH	3D	UfPPP

Example of a subroutine to delay for a certain amount of time

; Subroutine to wait for $100\ \mathrm{ms}$

- Want inner loop to last for 1 ms. MC9S12 runs at 24,000,000 cycles/second, so 1 ms is 24,000 cycles.
- Inner loop should be 24,000 cycles/ (3 cycles/loop) = 8,000 times
- Problem: The subroutine changes the values of registers A and X
- ullet To solve, save the values of A and X on the stack before using them, and restore them before returning.

; Subroutine to wait for 100 ms

```
delay:
        psha
                          ; Save regs used by sub on stack
        pshx
        ldaa
                #100
                          ; Execute outer loop 100 times
loop2:
        ldx
                #8000
                          ; Want inner loop to last 1 ms
                          ; Inner loop -- 3 cycles x 8000 times
loop1:
        dbne
                x,loop1
                a,loop2
        dbne
        pulx
                          ; Restore regs in opposite
        pula
                          ; order
        rts
```

```
; Program to make a binary counter on LEDs
; The program uses a subroutine to insert a delay
; between counts
; Does not work on Dragon12-Plus. Need to write to PTJ
; to enable LEDs
prog:
        equ
                $2000
                $1000
data:
        equ
STACK:
        equ
                $2000
PORTB:
        equ
                $0001
DDRB:
        equ
                $0003
        org
                prog
        lds
                            ; initialize stack pointer
                #STACK
        ldaa
                #$ff
                            ; put all ones into DDRA
        staa
                DDRB
                             ; to make PORTB output
        clr
                PORTB
                            ; put $00 into PORTB
                            ; wait a bit
loop:
        jsr
                delay
                PORTB
                            ; add one to PORTB
        inc
        bra
                loop
                             ; repeat forever
; Subroutine to wait for 100 ms
                         ; Save regs used by sub on stack
delay:
        psha
        pshx
        ldaa
                         ; Execute outer loop 100 times
                #100
                         ; Want inner loop to last 1 ms
loop2:
        ldx
                #8000
                         ; Inner loop -- 3 cycles x 8000 times
loop1:
        dbne
                x,loop1
        dbne
                a,loop2
        pulx
                         ; Restore regs in opposite
        pula
                          ; order
        rts
```

JSR and BSR place return address on stack RTS returns to instruction after JSR or BSR

0x1EF5 0x01E6	\	STACK: EQU ORG 2000 CF 20 00 LDS 2003 16 10 07 JSR 2006 7F SWI 2007 CE 12 34 MY_SUB: LDX	\$2000 \$2000 #STACK MY_SUB
0x1EF7		2 ₍ 00A 3D RTS	
0x1EF8			
0x1EF9		A .	В
0x1EFA		D .	
0x1EFB			
0x1EFC		Х	
0x1EFD		Υ	
0x1EFE			
0x1EFF		SP	
0x1F00		PC	
0x1F01			
0x1F02		CCR	
0x1F03			
	•		

Another example of using a subroutine

Using a subroutine to wait for an event to occur, then take an action.

- Wait until bit 7 of address \$00C4 is set.
- Write the value in ACCA to address \$00C7.

```
; This routine waits until the MC9S12 serial ; port is ready, then sends a byte of data ; to the MC9S12 serial port putchar: brclr $00CC, #$80, putchar staa $00CF rts
```

• Program to send the word hello, world! to the MC9S12 serial port

```
; Program fragment to write the word "hello, world!" to the ; MC9S12 serial port \,
```

```
ldx
                        $str
loop:
             ldaa
                        1,x+
                                 ; get next char
                        done
                                 ; char == 0 => no more
             beq
             jsr
                        putchar
             bra
                        loop
             swi
             dc.b
                        "hello, world!"
str:
                        $0A,$0D,0
             fc.b
                                      ; CR LF
```

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Here is the complete program to write a line to the screen:

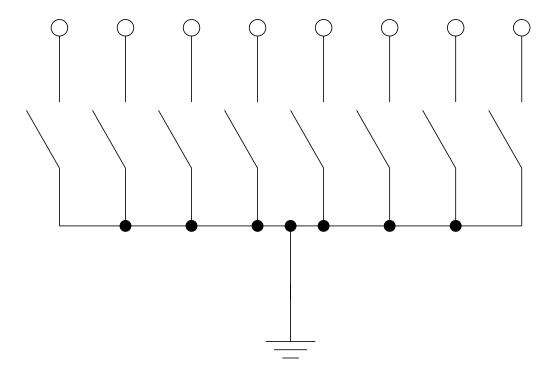
Freescale HC12-Assembler (c) Copyright Freescale 1987-2009

Abs.	Rel.	Loc	Obj.	code	Source 1:	ine	
1	1		0000	2000	prog:	equ	\$2000
2	2			1000	data:	_	\$1000
3	3		0000	2000	stack:	_	\$2000
4	4		0000	OOCC	SCIOSR1:		\$00CC ; SCIO status reg 1
5	5		0000	OOCF	SCIODRL:		\$00CF ; SCIO data reg low
6	6					•	·
7	7					org	prog
8	8	a002000	CF20	00		lds	#stack
9	9	a002003	CE10	00		ldx	#str
10	10	a002006	A630		loop:	ldaa	1,x+; get next char
11	11	a002008	2705		-	beq	done; char == 0 => no more
12	12	a00200A	1620	10		jsr	putchar
13	13	a00200D	20F7			bra	loop
14	14	a00200F	3F		done:	swi	
15	15						
16	16	a002010	4FCC	80FC	<pre>putchar:</pre>	brclr	SCIOSR1,\$80,putchar
17	17	a002014	5ACF			staa	SCIODRL
18	18	a002016	3D			rts	
19	19						
20	20					org	data
21	21	a001000	6865	6C6C	str:	fcc	"hello, world!"
		001004	6F2C	2077			
		001008	6F72	6C64			
		00100C	21				
22	22	a00100D	OAOD	00		dc.b	<pre>\$0a,\$0d,0 ; CR LF terminating zero</pre>
23	23						

Using DIP switches to get data into the MC9S12

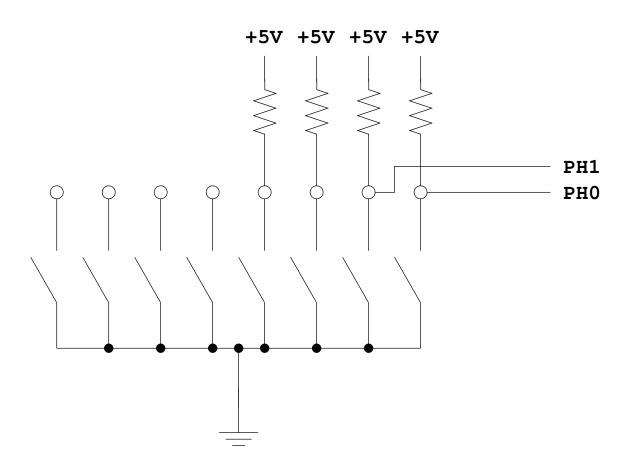
• DIP switches make or break a connection (usually to ground)

DIP Switches on Breadboard



- To use DIP switches, connect one end of each switch to a resistor
- Connect the other end of the resistor to +5 V
- Connect the junction of the DIP switch and the resistor to an input port on the MC9S12
- The Dragon12-Plus has eight dip switches connected to Port H (PTH).

Using DIP Switches



- When the switch is open, the input port sees a logic 1 (+5 V)
- When the switch is closed, the input sees a logic 0 (0 V)

Looking at the state of a few input pins

- Want to look for a particular pattern on 4 input pins
 - For example want to do something if pattern on PB3-PB0 is 0110
- Don't know or care what are on the other 4 pins (PB7-PB4)
- Here is the wrong way to do it:

ldaa PTH cmpa #\$06 beq task

- If PH7-PH4 are anything other than 0000, you will not execute the task.
- You need to mask out the Don't Care bits **before** checking for the pattern on the bits you are interested in

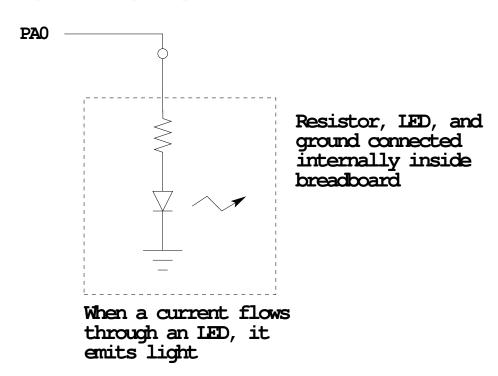
ldaa PTH anda #\$0F cmpa #\$06 beq task

• Now, whatever pattern appears on PB7-4 is ignored

Using an MC9S12 output port to control an LED

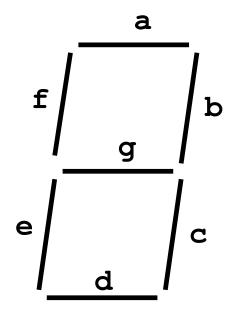
• Connect an output port from the MC9S12 to an LED.

Using an output port to control an LED



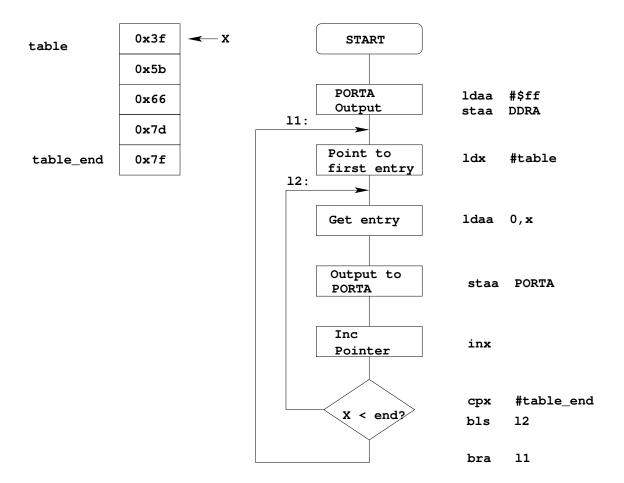
Making a pattern on a seven-segment LED

• Want to generate a particular pattern on a seven-segment LED:



- Determine a number (hex or binary) which will generate each element of the pattern
 - For example, to display a 0, turn on segments a, b, c, d, e and f, or bits 0,
 1, 2, 3, 4 and 5 of PTB. The binary pattern is 00111111, or \$3f.
 - To display 0 2 4 6 8, the hex numbers are \$3f, \$5b, \$66, \$7d, \$7f.
- Put the numbers in a table
- Go through the table one by one to display the pattern
- When you get to the last element, repeat the loop

Flowchart to display a pattern of lights on a set of LEDs



; Program using subroutine to make a time delay

prog: data: stack: PORTB: DDRB:	equ equ equ equ	\$2000 \$1000 \$2000 \$0001 \$0003		
	org	prog		
11: 12:	lds ldaa staa ldx ldaa staa jsr cpx bls bra	<pre>#stack #\$ff DDRB #table 1,x+ PORTB delay #table_end 12 11</pre>	;;	Yes, keep going through table
delay:	psha pshx			
loop2: loop1:	ldaa ldx dbne dbne pulx pula rts	#100 #8000 x,loop1 a,loop2		
<pre>table: table_end:</pre>	org dc.b dc.b dc.b dc.b	data \$3f \$5b \$66 \$7d \$7F		