1. How do you set up the HC12 to use the SPI in the following mode. Write some C code to do this.

   - HC12 is the master
   - No interrupts
   - SCK idle low, data valid on rising edge of SCK
   - LSB is sent first
   - SCK frequency is 250 kHz

2. Explain how the SPIF (SPI Flag) is set. Also, explain how to clear this flag.

3. A 68HC12 is being used to communicate with two devices over the SPI. The devices are connected as shown below:

   ![Diagram of SPI connection](image.png)

   Each byte you write to the LCD chip is displayed on an LCD display. The following shows how to write to the LCD chip over the SPI:

   ![Diagram of SPI write](image.png)

   The GP2D device is a distance sensor. When the HC12 reads from the GP2D chip, the GP2D sends it a byte which tells it how far it is from an object (such as a wall). The GP2D sends a 0x00 when it is almost touching the object. It sends a 0xFF when it is 2 feet (or more) from the object. The following shows how to read from the GP2D chip over the SPI:
(a) How do you set up the HC12 to communicate with the LCD and the GP2D? Explain what values you need to write to which registers. Be sure to set the correct clock phase and polarity.

(b) Write some C code to set up the HC12 to communicate with the LCD chip and the GP2D chip – i.e., write C code to implement (1).

(c) Write some C code to read the distance from the GP2D. Make sure the LCD chip is deselected while you are doing this.

(d) Write some C code to sent the sequence "Hello" to the LCD chip. Make sure the GP2D is deselected while you are doing this.

4. Look at the data sheet for the MAX522 D/A converter. Determine how to talk to the MAX522 over the SPI.

   (a) What SPI clock rate should you use?
   (b) What clock polarity and phase?
   (c) Should you use most significant bit first or least significant bit first?
   (d) How many bytes are transferred to write a new data value to the MAX522 – one byte, two bytes, or four bytes?

5. Assume the MAX522 is connected as shown in Lab 10.

   (a) Write some C code to set up the SPI to talk to the MAX522.
   (b) Write some C code to have the MAX522 put out 0.125 V on OUTA and 0.325 V on OUTB.