

**EE 341 - Homework 6****Due October 7, 2005**

For problems which require MATLAB, please include a MATLAB m-file which shows how you made your plots.

1. Find the Fourier transforms of the following signals:

- (a)  $x(t) = e^{-2t} \cos(2\pi t)u(t)$
- (b)  $x(t) = \cos^2(2\pi t) \sin(2\pi t)$
- (c)  $x(t) = \text{sinc}(t) * \text{sinc}(2t)$
- (d)  $x(t) = (1 - e^{-t})u(t)$

2. Sketch the spectra ( $|X(\omega)|$  and  $\angle X(\omega)$ ) for the following signals:

- (a)  $x(t) = \text{sinc}(t - 2)$
- (b)  $x(t) = \text{sinc}^2(t) \cos(8\pi t)$
- (c)  $x(t) = \cos(\pi t - 0.25\pi)$
- (d)  $x(t) = \cos(\pi t)p_1(t)$
- (e)  $x(t) = \cos(\pi t)p_{100}(t)$

3. Find the Fourier transform of the following signals and sketch their spectra ( $|X(\omega)|$  and  $\angle X(\omega)$ ):

- (a)  $x(t) = \delta(t + 1) + \delta(t - 1)$
- (b)  $x(t) = \delta(t + 1) - \delta(t - 1)$

4. Sketch the spectra ( $|Y(\omega)|$  and  $\angle Y(\omega)$ ) where  $y(t) = m(t)x(t)$  (the signal  $x(t)$  which has been modulated by the signal  $m(t)$ ):

- (a)  $X(\omega) = p_1(\omega)$   $m(t) = \cos(\pi t)$
- (b)  $X(\omega) = p_4(\omega)$   $m(t) = \cos(\pi t)$
- (c)  $X(\omega) = p_1(\omega)$   $m(t) = \cos(10\pi t)$

5. Problem 4.24.

EE 341 HW #6

$$1.(a) x(t) = e^{-2t} \cos(2\pi t) u(t)$$

$$e^{-2t} u(t) \Leftrightarrow \frac{1}{j\omega + 2}$$

$$e^{-2t} \cos(2\pi t) u(t) \Leftrightarrow \frac{1}{2} \left[ \frac{1}{j(\omega + 2\pi) + 2} + \frac{1}{j(\omega - 2\pi) + 2} \right]$$

$$(b) x(t) = \cos^2(2\pi t) \sin(2\pi t)$$

$$\sin(2\pi t) \Leftrightarrow j\pi [\delta(\omega + 2\pi) - \delta(\omega - 2\pi)]$$

$$\begin{aligned} \cos(2\pi t) \sin(2\pi t) &\Leftrightarrow j\pi [\delta(\omega + 2\pi + 2\pi) - \delta(\omega - 2\pi + 2\pi) \\ &\quad + \delta(\omega + 2\pi - 2\pi) - \delta(\omega - 2\pi - 2\pi)] \\ &= j\pi [\delta(\omega + 4\pi) - \delta(\omega - 4\pi)] \end{aligned}$$

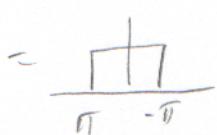
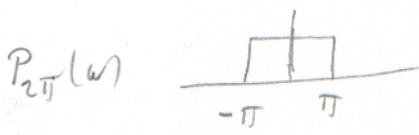
$$\begin{aligned} \cos^2(2\pi t) \sin(2\pi t) &\Leftrightarrow j\pi [\delta(\omega + 4\pi + 2\pi) - \delta(\omega - 4\pi + 2\pi) \\ &\quad + \delta(\omega + 4\pi - 2\pi) - \delta(\omega - 4\pi - 2\pi)] \\ &= j\pi [\delta(\omega + 6\pi) + \delta(\omega + 2\pi) \\ &\quad - \delta(\omega - 2\pi) - \delta(\omega - 6\pi)] \end{aligned}$$

$$(c) x(t) = \text{sinc}(t) * \text{sinc}(2t)$$

$$\text{sinc}(t) = \frac{1}{2\pi} [2\pi \text{sinc}\left(\frac{2\pi t}{2\pi}\right)] \Leftrightarrow \frac{1}{2\pi} (2\pi P_{2\pi}(\omega))$$

$$\text{sinc}(2t) = \frac{1}{4\pi} [4\pi \text{sinc}\left(\frac{4\pi t}{2\pi}\right)] \Leftrightarrow \frac{1}{4\pi} (2\pi P_{4\pi}(\omega))$$

$$\begin{aligned} \text{sinc}(t) * \text{sinc}(2t) &\Leftrightarrow \frac{1}{2\pi} (2\pi P_{2\pi}(\omega)) \frac{1}{4\pi} (2\pi P_{4\pi}(\omega)) \\ &= \frac{1}{2} P_{2\pi}(\omega) P_{4\pi}(\omega) \end{aligned}$$



$$\text{sinc}(t) * \text{sinc}(2t) \Leftrightarrow \frac{1}{2} P_{2\pi}(\omega)$$

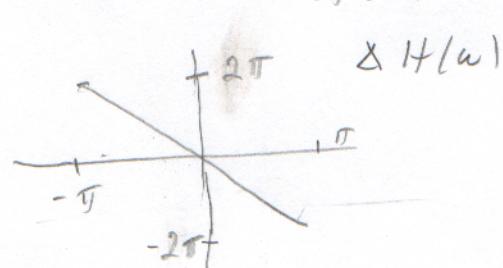
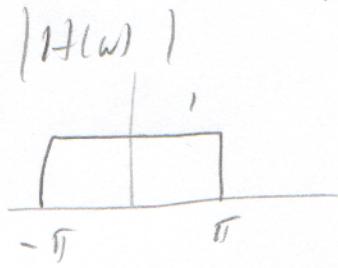
(2)

$$(d) x(t) = (1 - e^{-t}) u(t) = u(t) - e^{-t} u(t)$$

$$u(t) - e^{-t} u(t) \Leftrightarrow \pi \delta(\omega) + \frac{1}{j\omega} + \frac{1}{j\omega+1}$$

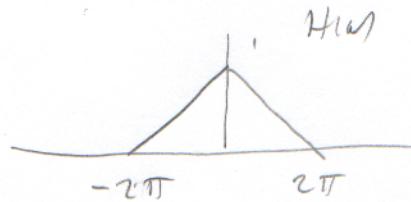
$$2(a) x(t) = \text{sinc}(t-2) \quad \text{sinc}(t) \Leftrightarrow P_{2\pi}(\omega)$$

$$\text{sinc}(t-2) \Leftrightarrow e^{-j2\omega} P_{2\pi}(\omega)$$

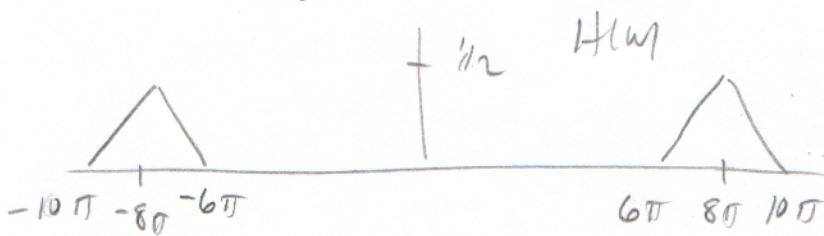


$$(b) x(t) = \text{sinc}^2(t) \cos(8\pi t)$$

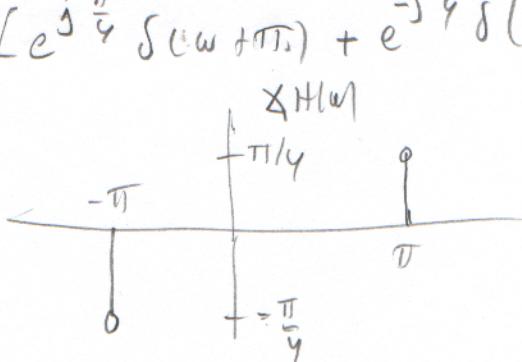
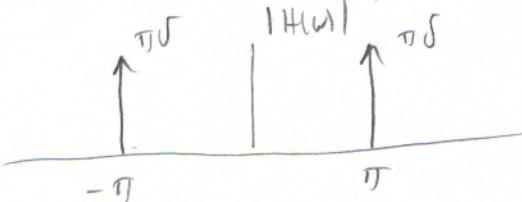
$$\text{sinc}^2(t) = \frac{1}{2\pi} \left[ \frac{4\pi}{2} \text{sinc}^2 \left( \frac{4\pi t}{4\pi} \right) \right] \Leftrightarrow \frac{1}{2\pi} \left[ 2\pi \left( 1 - \frac{2|\omega|}{4\pi} \right) P_{4\pi}(\omega) \right]$$



Multiply by  $\cos(8\pi t)$  shifts by  $\pm 8\pi$  and scales by  $\frac{1}{2}$



$$(c) x(t) = \cos(\pi t - 0.25\pi) \Leftrightarrow \pi \left[ e^{j\frac{\pi}{4}} \delta(\omega + \pi) + e^{-j\frac{\pi}{4}} \delta(\omega - \pi) \right]$$



(3)

$$(d) X(t) = \cos(\pi t) P_1(t)$$

$$P_1(t) \Leftrightarrow \text{sinc}\left(\frac{\omega}{2\pi}\right)$$

$$\cos(\pi t) P_1(t) \Leftrightarrow \text{sinc}\left(\frac{\omega+\pi}{2\pi}\right) + \text{sinc}\left(\frac{\omega-\pi}{2\pi}\right)$$

See MATLAB for plot

$$(e) X(t) = \cos(\pi t) P_{100}(t)$$

$$P_{100}(t) \Leftrightarrow 100 \text{sinc}\left(\frac{50\omega}{\pi}\right)$$

$$\cos(\pi t) P_{100}(t) \Leftrightarrow 100 \text{sinc}\left(\frac{50(\omega+\pi)}{\pi}\right) + \text{sinc}\left(\frac{50(\omega-\pi)}{\pi}\right)$$

See MATLAB for plot

$$3. (a) X(t) = \delta(t+1) + \delta(t-1)$$

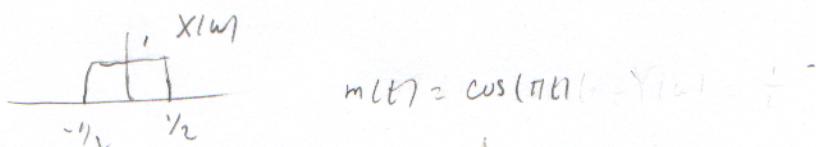
$$\delta(t) \Leftrightarrow 1$$

$$\delta(t+1) \Leftrightarrow e^{j\omega} \quad \delta(t-1) \Leftrightarrow e^{-j\omega}$$

$$\delta(t+1) + \delta(t-1) \Leftrightarrow e^{j\omega} + e^{-j\omega} = 2 \cos(\omega)$$

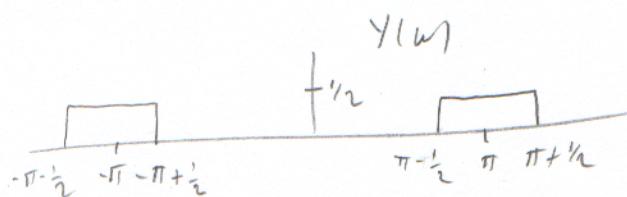
$$(b) X(t) = \delta(t+1) - \delta(t-1) \Leftrightarrow e^{j\omega} - e^{-j\omega} = 2j \sin(\omega)$$

$$4. (a) X(\omega) = P_1(\omega)$$



$$m(t) = \cos(\pi t)(1 - Y(\omega)) = \frac{1}{2}$$

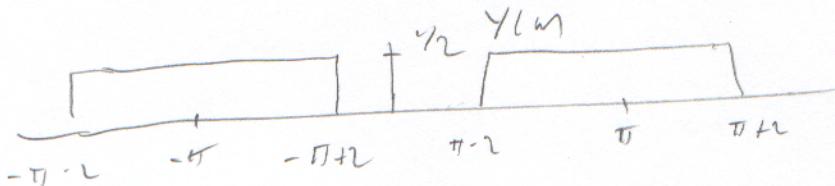
$$Y(\omega) = \frac{1}{2} [X(\omega+\pi) + X(\omega-\pi)] = \frac{1}{2} [P_1(\omega+\pi) + P_1(\omega-\pi)]$$



(4)

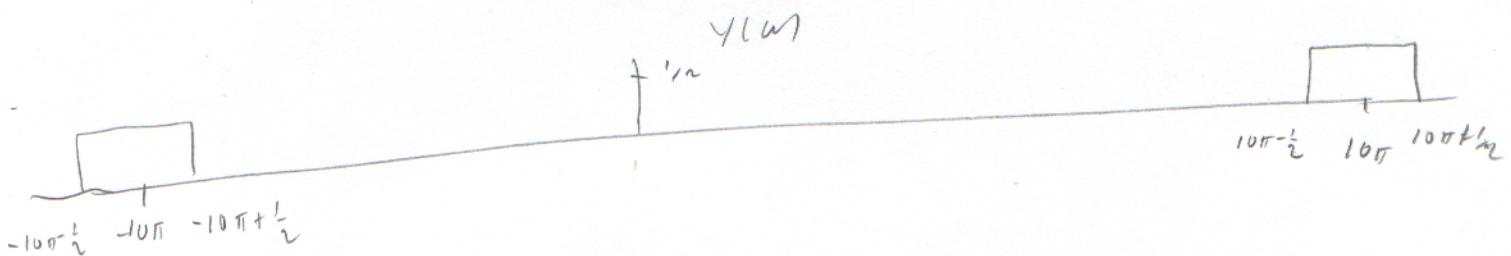
$$(b) X(\omega) = P_4(\omega) \quad \begin{array}{c} X(\omega) \\ \hline -2 & 0 & 2 \end{array} \quad m(t) = \cos(\pi t)$$

$$Y(\omega) = \frac{1}{2} [P_4(\omega + \pi) + P_4(\omega - \pi)]$$



$$(c) X(\omega) = P_1(\omega) \quad \begin{array}{c} X(\omega) \\ \hline -\frac{1}{2} & \frac{1}{2} \end{array} \quad m(t) = \cos(10\pi t)$$

$$Y(\omega) = \frac{1}{2} [P_1(\omega + 10\pi) + P_1(\omega - 10\pi)]$$



### 5. Problem 4.24

$$X(\omega) = \begin{cases} 2 & |\omega| < \pi \\ 0 & \text{otherwise} \end{cases} = 2P_{2\pi}(\omega)$$

$$V(\omega) = X(\omega - \omega_0) + X(\omega + \omega_0) \Rightarrow v(t) = 2X(t) \cos(\omega_0 t)$$

$$(a) 2P_{2\pi}(\omega) = \frac{1}{\pi} (2\pi P_{2\pi}(\omega)) \Leftrightarrow \frac{1}{\pi} (2\pi \sin(\frac{2\pi t}{2\pi})) = 2 \sin(t)$$

$$(b) v(t) = 2 \cos(\omega_0 t) \quad x(t) = 4 \cos(\omega_0 t) \sin(t)$$

```
% EE 341 HW #6

% Problem 3
figure(1)
clf

% (d)
w = -30:0.001:30;
X = sinc((w+pi)/(2*pi)) + sinc((w-pi)/(2*pi));
subplot(211)
plot(w,X);
grid
ylabel('x_d(\omega)')
title('HW #6 Problem 4 (d) (e)')

% (e)
w = -5:0.001:5;
X = sinc(50*(w+pi)/pi) + sinc(50*(w-pi)/pi);
subplot(212)
plot(w,X);
grid
ylabel('x_e(\omega)')
xlabel('\omega')

print -dpsc2 hw6_p4.ps
```

HW #6 Problem 4 (d) (e)

